



**LUNDS UNIVERSITET**  
Lunds Tekniska Högskola

*Course syllabus*

# Mekanik

## Engineering Mechanics

**FMEA30, 15 credits, G1 (First Cycle)**

**Valid for:** 2023/24

**Faculty:** Faculty of Engineering, LTH

**Decided by:** PLED M

**Date of Decision:** 2023-04-11

### General Information

**Main field:** Technology.

**Compulsory for:** M2, MD2

**Language of instruction:** The course will be given in Swedish

### Aim

- give knowledge about the basic concepts in mechanics for material systems at rest
- give knowledge about the basic concepts in mechanics for material systems in motion, mainly for particles, systems of particles and rigid bodies
- give knowledge and skills in engineering modelling
- develop ability to solve problems by using the computer softwares MATLAB and ADAMS

### Learning outcomes

*Knowledge and understanding*

For a passing grade the student must

- be able to define and apply fundamental concepts such as force and moment of force, linear and angular momentum, impulse and moment of impulse, and be able to express them both in scalar and vector form
- be able to draw a free body diagram of a material body and to set up the equations of equilibrium and motion

- be able to describe velocities and accelerations in Cartesian, polar and natural coordinates systems and use the the force and moment equations for a particle
- be able to use the velocity and acceleration fields in rigid body motion
- be able to define and use the basic concepts linear momentum, angular momentum, impulse and moment of impulse, moment of inertia, power, energy and work for a rigid body
- be able to use the force and moment equations to describe plane rigid body motion
- be able to analyze practical problems in mechanics
- be able to use MATLAB in the solution of problems in mechanics

### *Competences and skills*

For a passing grade the student must

- starting with a real situation be able to delimit a problem and perform an equilibrium analysis
- be able to apply systematic methods in an analysis of mechanical systems in equilibrium and particles in motion
- starting with a real situation be able to delimit a problem and treat material bodies as particles or rigid bodies
- be able to apply systematical methods to mechanical systems in motion
- be able to present written solutions to mechanical problems with suitable drawing and free body diagrams
- given a project specification be able to delimit a problem and create a model which may be analyzed using in a simulation software.

### *Judgement and approach*

For a passing grade the student must

- evaluate the physical consistency of the obtained results

## **Contents**

**Statics:** Moment and force systems in 2 and 3 dimensions. Free-body diagrams and equilibrium of material bodies. Equilibrium in frames. Distributed forces, centre of mass, flexible cables. Friction. Potential energy and stability.

**Dynamics:** Newton's laws. Kinematics and kinetics of particles in straight and curved motion, natural and polar co-ordinates. Energy and work. Momentum and impulse, moments of momentum and impulse moments. Impact. Kinematics of system of particles (general) and rigid bodies (plane). Energy, work, linear and angular impulse and momentum. Impact. Newtons laws. Kinetic for particles in 2D and 3D and kinetic for rigid bodies in plane motion. Rotating coordinate systems. Vibrations of damped and undamped mechanical systems. Free and forced vibrations. Natural frequencies and

vibration analysis.

**MATLAB:** Numerical calculations, writing scripts, defining functions, graphics, symbolic calculations differentiation and integration, solving equations, differential equations, linear algebra

## Examination details

**Grading scale:** TH - (U,3,4,5) - (Fail, Three, Four, Five)

**Assessment:** Written examinations. Approved project report. Approved assignments.

The examiner, in consultation with Disability Support Services, may deviate from the regular form of examination in order to provide a permanently disabled student with a form of examination equivalent to that of a student without a disability.

### Parts

**Code:** 0113. **Name:** Statics and Particle Dynamics.

**Credits:** 7. **Grading scale:** TH. **Assessment:** Written exam. (part)

**Code:** 0213. **Name:** Dynamics.

**Credits:** 5. **Grading scale:** TH. **Assessment:** Written exam.

**Code:** 0313. **Name:** Project.

**Credits:** 0. **Grading scale:** UG. **Assessment:** Approved project report.

**Code:** 0413. **Name:** Assignment 1.

**Credits:** 1,5. **Grading scale:** UG. **Assessment:** Approved hand-in.

**Code:** 0513. **Name:** Assignment 2.

**Credits:** 1,5. **Grading scale:** UG. **Assessment:** Approved hand-in.

## Admission

**Assumed prior knowledge:** FMA420 Linear algebra, FMAA01/05 Calculus in One Variable.

**The number of participants is limited to:** No

**The course overlaps following course/s:** FMEA01, FMEA25, FMEA05, FMEA20, FMEA10, FMEA15

## Reading list

- C.Nyberg: Mekanik : statik. Liber, 2014, ISBN: 9789147114429.
- C. Nyberg: Mekanik - Partikeldynamik. Liber, 2014, ISBN: 9789147114436.
- C. Nyberg: Mekanik - Stelkroppsdyamik. Liber, 2014, ISBN: 9789147114443.
- William J. Palm III: A Concise Introduction to MATLAB, International Edition. McGraw Hill, 2008.

## Contact and other information

**Course coordinator:** Per Hansson, per.hansson@mek.lth.se

**Course homepage:** <http://www.mek.lth.se/Education>

**Further information:** Parts of the course may be in English.